

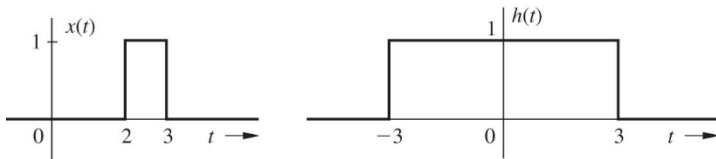
ENGR 3323: Signals and Systems

HW 4\_Ch2

1) The unit impulse response of an LTIC system is  $h(t) = e^{-2t} u(t)$ . Find this system's (zero-state) response  $y(t)$  if the input  $x(t)$  is

- a)  $2u(t)$       b)  $e^{-t} u(t)$       c)  $\sin 3t u(t)$       d) the pulse  $2\Pi\left(\frac{t-1}{2}\right)$       e)  $\delta(t)$       f)  $\delta(t-2)$

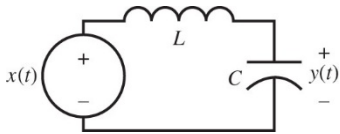
2) Figure below shows the input  $x(t)$  and the impulse response  $h(t)$  for an LTIC system. Let the output be  $y(t)$ .



a. By inspection of  $x(t)$  and  $h(t)$ , find  $y(-1)$ ,  $y(0)$ ,  $y(1)$ ,  $y(2)$ ,  $y(3)$ ,  $y(4)$ ,  $y(5)$ , and  $y(6)$ . Thus, by merely examining  $x(t)$  and  $h(t)$ , you are required to see what the result of convolution yields at  $t = -1, 0, 1, 2, 3, 4, 5$ , and  $6$ .

b. Find the system response to the input  $x(t)$ .

3) Consider the electric circuit shown below.



a. Determine the differential equation that relates the input  $x(t)$  to output  $y(t)$ .

b. Find the characteristic equation for this circuit, and express the root(s) of the characteristic equation in terms of  $L$  and  $C$ .

c. Determine the zero-input response given an initial capacitor voltage of one volt and an initial inductor current of zero amps. That is, find  $y_0(t)$  given  $v_c(0) = 1$  V and  $i_L(0) = 0$  A. [Hint: The coefficient(s) in  $y_0(t)$  are independent of  $L$  and  $C$ .]

d. Plot  $y_0(t)$  for  $t \geq 0$ . Does the zero-input response, which is caused solely by initial conditions, ever "die" out?

e. Determine the total response  $y(t)$  to the input  $x(t) = e^{-t}u(t)$ . Assume an initial inductor current of  $i_L(0^-) = 0$  A, an initial capacitor voltage of  $v_c(0^-) = 1$  V,  $L = 1$  H, and  $C = 1$  F.

4) Explain, with reasons, whether the LTIC systems described by the following equations are (i) stable or unstable in the BIBO sense; (ii) asymptotically stable, unstable, or marginally stable. Assume that the systems are controllable and observable.

a.  $(D^2 + 8D + 12)y(t) = (D - 1)x(t)$

b.  $D(D^2 + 3D + 2)y(t) = (D + 5)x(t)$

c.  $D^2(D^2 + 2)y(t) = x(t)$

d.  $(D + 1)(D^2 - 6D + 5)y(t) = (3D + 1)x(t)$

5) Determine a frequency  $\omega$  that will cause the input  $x(t) = \cos(\omega t)$  to produce a strong response when applied to the system described by  $(D^2 + 2D + 13/4)y(t) = x(t)$ . Carefully explain your choice.